Exam 1 Review (Chapters 1-4, 6-9)

Types of questions

- Definitions
- Short questions
- Comparisons
- Problem solving (simple problems)
- Proofs

• State Space

- States, state transition rules/operators/actions, and costs associate with operations
- State space, node generation and **node expansion**, open/closed nodes, open/closed lists.
- Solution, solution path and its cost.
- Be able to represent simple problem-solving as state space search

• Uninformed (blind) Search Methods

- Search methods (BF, DF, **IDDF**, **Uniform-cost**), their algorithms, time and space complexities, optimality and completeness, their advantages and limitations.

• Informed Search methods

- Evaluation function f(n),
- Heuristic estimate function h(n)
 - \circ what does h(n) estimate
 - \circ admissible h(n), null h(n), perfect h*(n), more informed h(n)
- Best first search:
 - \circ node selection from open list according to f(n)
 - o delayed goal testing
- Algorithm A and A*
 - \circ f(n) = g(n) + h(n): what does each of the terms stand for?
 - algorithm (maintaining open/closed lists, delayed goal test; node expansion, handling duplicate nodes, back pointers);
 - difference between algorithms A and A*
 - time and space complexity, completeness and optimality of A*
 - \circ be able to apply A* to simple problems.
 - Be able to prove simple properties related to A* search
- Ways to improve A* search
 - IDA* (basic idea; how to set f_limit at each iteration; advantages over A*)
 - Pruning open list by f+, where f+ is an upper bound of the cost for the optimal solution (e.g., the cost of any known solution)
- Greedy search and hill-climbing (algorithms, time and space complexity, completeness and optimality)
- Basic ideas of simulated annealing for seeking optimal solutions

• Game-Tree Search

- Game tree (Max and Min nodes; look ahead, terminal and leave nodes)

- What to search for (one move for Max with maximum guaranteed payoff)
- Heuristic evaluation function f(n) (merit of a board configuration)
- Minimax rule for game tree search
- Alpha-beta pruning, its time and space complexities.
- Difference between general state space search and game tree search
- Be able to apply Minimax rule and alpha-beta pruning to simple problems.

• Propositional Logic (PL)

- Syntax
- Semantics
 - Interpretation (an assignment of truth values to all prepositional symbols); models
 - Truth tables for logical connectives
 - Valid (tautology), satisfiable and inconsistent (contradiction) sentences
 - Logical consequence or entailment (S \models X)
- Equivalence laws
 - $\circ P \equiv Q$ iff they have the same truth tables
 - \circ P => Q = ~P v Q; distribution /associative/communicative laws, De Morgan's laws
- Deductive inference
 - Using truth table (S $\mid = X$ iff S $\Rightarrow X$ is valid)
 - Using deductive rules
 - Modus Ponens, Modus Tollens, Chaining, And Introduction, And Elimination, etc.
 - Soundness of deductive rules
 - **Resolution rule** (and CNF)
 - Proof procedure, Soundness and completeness of proof procedures

• First Order Logic (FOL)

- Syntax
 - o Terms, predicates, atoms, literals, quantifiers, wff
- Semantics
 - Interpretations and models, valid, satisfiable, and inconsistent sentence(s), Logical consequences
 - Be able to translate between English sentences and FOL sentences
 - o Soundness and completeness of proof theory in FOL

• Deductive Inference in FOL

- Convert first order sentences to clause form
 - Definition of clauses, converting FOL sentences to clause form (Skolemization)
- Unification (obtain mgu θ)
- Resolution
- Resolution Refutation
 - Write the axioms as FOL sentences and convert them into clause form
 - Write the goal (theorem) as a FOL sentence
 - Negate the goal and convert it to clause form
 - Select a pair of clauses for resolution which are i) resolvable, and ii) promising toward deriving a null clause,

- Inference stops when a null clause is derived
- Be able to do resolution refutation on simple problems.
- Other issues
 - o Semi-decidability
 - Forward and backward chaining