CMSC 611: Advanced Computer Architecture

Branch Prediction

Some material adapted from Mohamed Younis, UMBC CMSC 611 Spr 2003 course slides Some material adapted from Hennessy & Patterson / © 2003 Elsevier Science

Recall Branch Penalties

- CPI = (1-branch%) * non-branch CPI + branch% * branch CPI
- CPI = (1-branch%) * 1
 + branch% * (1 + penalty)
- CPI = 1 + (branch% * penalty)
- penalty = not taken% * not taken cost
 + taken% * taken cost

Branching Dilema

- Instruction Level Parallelism increases throughput
 - Worse, the more advanced the method
 - Deep pipeline, multiple functional units, n-issue per clock, …
- Control dependence rapidly becomes the limiting factor to the amount of ILP
- Compiler-based techniques can only rely on static program properties to handle control hazards
- Hardware-based techniques refer to the dynamic behavior of the program to predict the outcome of a branch

Recall 5-stage Prediction

Assume

- 20% of instructions are branches
- 53% of branches are taken
- Predict not taken

- CPI = 1 + 20% * (53%*1 + 47%*0) = 1.106

Predict taken
 Penalty for being wrong

-CPI = 1 + 20% * (53%*1 + 47%*1) = 1.2

Penalty for being wrong

Penalty for not having the address ready in time

Branch Target Cache

- Predict not-taken: still stalls to wait for branch target computation
- If address could be guessed, the branch penalty becomes zero
- Cache predicted address based on branch address
- Complications for complex predictors: do we know in time?

Branch Target Cache



Handling Branch Target Cache

- No branch delay if the a branch prediction entry is found and is correct
- A penalty of two cycle is imposed for a wrong prediction or a cache miss
- Cache update on misprediction and misses can extend the time penalty
- Dealing with misses or misprediction is expensive and should be optimized



Return Address Cache

- Branch target caching can be applied to expedite unconditional jumps (branch folding) and returns for procedure calls
- For calls from multiple sites, not clustered in time, a stack implementation of the branch target cache can be useful



Basic Branch Prediction

- Simplest dynamic branch-prediction scheme
 - Use a branch history table to track when the branch was taken and not taken
 - Branch history table is a small 1-bit buffer indexed by lower bits of PC address with the bit is set to reflect the whether or not branch taken last time
- **Performance** = *f*(accuracy, cost of misprediction)
- Problem: in a nested loop, 1-bit branch history table will cause two mispredictions:
 - End of loop case, when it exits instead of looping
 - First time through loop on next time through code, when it predicts exit instead of looping

2-bit Branch History Table

- A two-bit buffer better captures the history of the branch instruction
- A prediction must miss twice to change



N-bit Predictors

- 2-bit is a special case of n-bit counter
 - For every entry in the prediction buffer
 - Increment/decrement if branch taken/not
 - If the counter value is one half of the maximum value (2n-1), predict taken
- Slow to change prediction, but can change

Performance of 2-bit Branch Buffer



SPEC89 benchmarks

Optimal Size for 2-bit Branch Buffers

