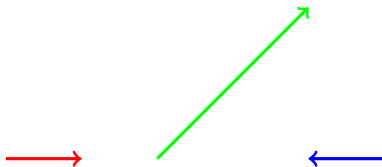


Linear Algebra Review

CMSC 435/634

Abstract Vectors

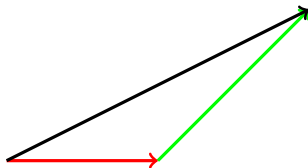
(\vec{u} , \vec{v} , \vec{w} vectors; a , b , c scalars)



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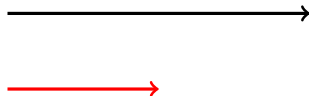
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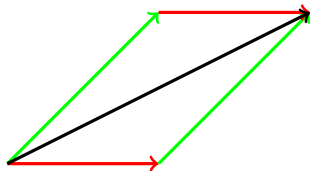
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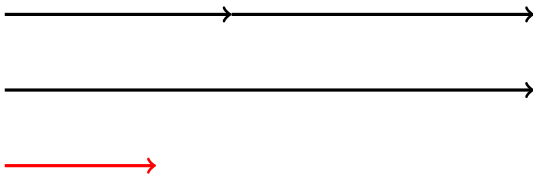
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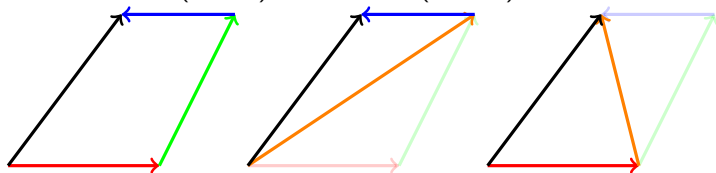
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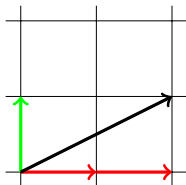
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Basis Vectors

Vector as linear combination of *basis vectors*

- $\vec{v} = 2\hat{i} + 1\hat{j} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$

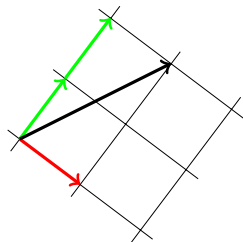


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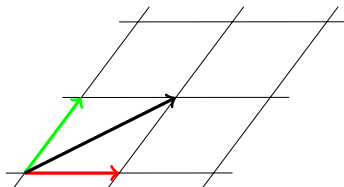
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 - Superscripts are just indices (borrowed from tensors)
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- I like columns for points/vectors, rows for normals

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- $a_\alpha^i b_j^\alpha$ is *Einstein Summation Notation*
 - Loop and sum over matching index variables

Einstein Summation and Code

- Math: $c_j^i = a_\alpha^i b_j^\alpha$
- Code:

```
for(int i=0; i<N; ++i) {  
    for(int j=0; j<M; ++j) {  
        c[i][j] = 0;  
        for(int alpha=0; alpha<K; alpha++) {  
            c[i][j] = c[i][j] + a[i][alpha] * b[alpha][j];  
        }  
    }  
}
```


Adjoint and Inverse

- Inverse: $A^{-1}A = AA^{-1} = I$
- Determinant: $|A|$
 - $|a| = a$
 - $\begin{vmatrix} a & b \\ c & d \end{vmatrix} = a|d| - b|c|$
 - $\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = a \begin{vmatrix} e & f \\ h & i \end{vmatrix} - b \begin{vmatrix} d & f \\ g & i \end{vmatrix} + c \begin{vmatrix} d & e \\ g & h \end{vmatrix}$
- Adjoint: $A^* = \text{cof}(A)^T$ (matrix of cofactors $\text{cof}(A)$)
- $A^{-1} = \frac{A^*}{|A|}$

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- Equivalent notations
 - Vector: $\vec{u} \bullet \vec{v}$
 - Matrix: $U^T V$
 - Summation: $u_\alpha v^\alpha$

Dot Defines Length and Angle

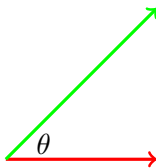
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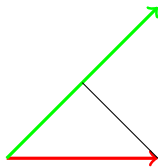
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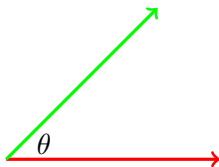
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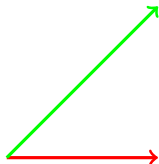
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- *Orthogonal matrix*: rows (& columns) **orthonormal**
 - For orthogonal matrices, $A^{-1} = A^T$

3D Cross Product

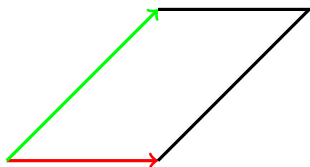
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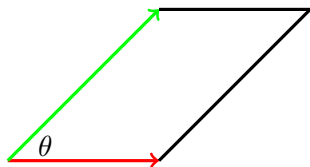
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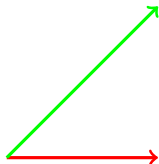
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Building an Orthogonal Basis

Vectors \vec{u} , \vec{v} , \vec{w}



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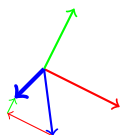
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- $\vec{v}' = \vec{v} - \vec{u}' \vec{v} \cdot \vec{u}' / \vec{u}' \cdot \vec{u}'$

- $\vec{w}' = \vec{w} - \vec{u}' \vec{w} \cdot \vec{u}' / \vec{u}' \cdot \vec{u}' - \vec{v}' \vec{w} \cdot \vec{v}' / \vec{v}' \cdot \vec{v}'$



Building an Orthogonal Basis

Vectors \vec{u} , \vec{v} , \vec{w}

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- $\vec{w}' = \vec{w} - \vec{u}' \vec{w} \bullet \vec{u}' / \vec{u}' \bullet \vec{u}' - \vec{v}' \vec{w} \bullet \vec{v}' / \vec{v}' \bullet \vec{v}'$



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- Cross-product (3D only)



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 - $\vec{w}' = \vec{w} - \vec{u}' \vec{w} \bullet \vec{u}' / \vec{u}' \bullet \vec{u}' - \vec{v}' \vec{w} \bullet \vec{v}' / \vec{v}' \bullet \vec{v}'$
- Cross-product (3D only)
 - $\vec{u}' = \vec{u}$



Building an Orthogonal Basis

Vectors \vec{u} , \vec{v} , \vec{w}

- Gram-Schmidt (any number of dimensions)

- $\vec{u}' = \vec{u}$

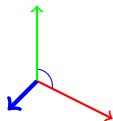
- $\vec{v}' = \vec{v} - \vec{u}' \vec{v} \bullet \vec{u}' / \vec{u}' \bullet \vec{u}'$

- $\vec{w}' = \vec{w} - \vec{u}' \vec{w} \bullet \vec{u}' / \vec{u}' \bullet \vec{u}' - \vec{v}' \vec{w} \bullet \vec{v}' / \vec{v}' \bullet \vec{v}'$

- Cross-product (3D only)

- $\vec{u}' = \vec{u}$

- $\vec{w}' = \vec{u}' \times \vec{v}'$



Building an Orthogonal Basis

Vectors \vec{u} , \vec{v} , \vec{w}

- Gram-Schmidt (any number of dimensions)

- $\vec{u}' = \vec{u}$

- $\vec{v}' = \vec{v} - \vec{u}' \frac{\vec{v} \cdot \vec{u}'}{\vec{u}' \cdot \vec{u}'}$

- $\vec{w}' = \vec{w} - \vec{u}' \frac{\vec{w} \cdot \vec{u}'}{\vec{u}' \cdot \vec{u}'} - \vec{v}' \frac{\vec{w} \cdot \vec{v}'}{\vec{v}' \cdot \vec{v}'}$

- Cross-product (3D only)

- $\vec{u}' = \vec{u}$

- $\vec{w}' = \vec{u}' \times \vec{v}$

- $\vec{v}' = \vec{w}' \times \vec{u}'$



Building an Orthogonal Basis

Vectors \vec{u} , \vec{v} , \vec{w}

- Gram-Schmidt (any number of dimensions)

- $\vec{u}' = \vec{u}$

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- $\vec{w}' = \vec{w} - \vec{u}' \vec{w} \bullet \vec{u}' / \vec{u}' \bullet \vec{u}' - \vec{v}' \vec{w} \bullet \vec{v}' / \vec{v}' \bullet \vec{v}'$

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