

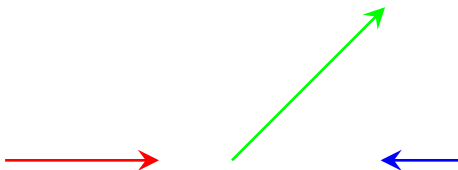
Vector Math

CMSC 435/634

Abstract Vectors

(\vec{u} , \vec{v} , \vec{w} vectors; a , b , c scalars)

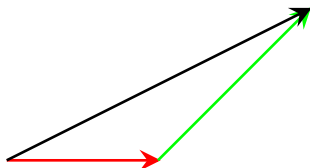
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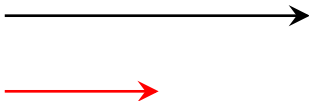
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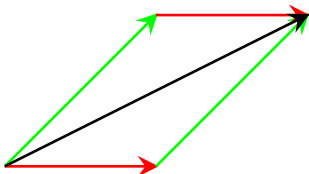
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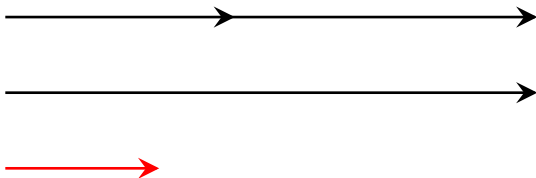
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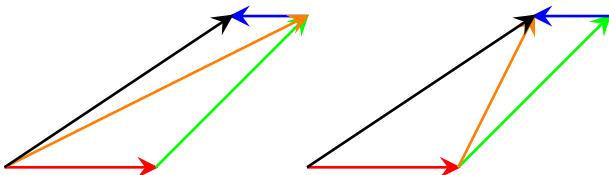
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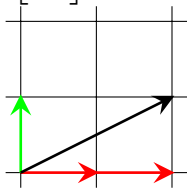
Basis Vectors

Vector as linear combination of *basis vectors*

$$\blacktriangleright \vec{v} = 2\hat{i} + 1\hat{j} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

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$$\blacktriangleright \vec{v} = 1\hat{p} + 1\hat{q} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$



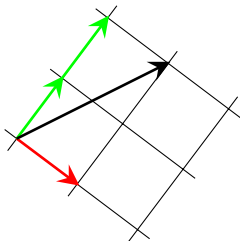
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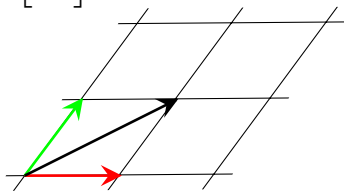
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$$\blacktriangleright \text{Column: } \vec{v} = \begin{bmatrix} v^0 \\ v^1 \end{bmatrix} \text{ (we'll usually use this form)}$$

$$\blacktriangleright \text{Row: } \vec{v} = [v_0 \quad v_1] \text{ (some texts; I like for normals)}$$

Matrices

- ▶ Matrix: $A = \begin{bmatrix} a_0^0 & a_1^0 \\ a_0^1 & a_1^1 \end{bmatrix} = [a_j^i]$
- ▶ Transpose: $A^T = \begin{bmatrix} a_0^0 & a_1^0 \\ a_0^1 & a_1^1 \end{bmatrix} = [a_i^j]$
- ▶ Multiply: $AB = \begin{bmatrix} a_0^0 & a_1^0 \\ a_0^1 & a_1^1 \end{bmatrix} \begin{bmatrix} b_0^0 & b_1^0 \\ b_0^1 & b_1^1 \end{bmatrix} =$
 $\begin{bmatrix} a_0^0 b_0^0 + a_1^0 b_0^1 & a_0^0 b_1^0 + a_1^0 b_1^1 \\ a_0^1 b_0^0 + a_1^1 b_0^1 & a_0^1 b_1^0 + a_1^1 b_1^1 \end{bmatrix} = [a_\alpha^i b_j^\alpha]$

Adjoint and Inverse

▶ Inverse: $A^{-1}A = AA^{-1} = I$

▶ Determinant: $|A|$

▶ $|a| = a$

▶ $\begin{vmatrix} a & b \\ c & d \end{vmatrix} = a|d| - b|c|$

▶ $\begin{vmatrix} a & b & c \\ c & d & e \\ f & g & h \end{vmatrix} = a \begin{vmatrix} d & e \\ g & h \end{vmatrix} - b \begin{vmatrix} c & e \\ f & h \end{vmatrix} + c \begin{vmatrix} c & d \\ f & g \end{vmatrix}$

▶ Adjoint: $A^* = \text{cof}(A)^T$ (matrix of cofactors $\text{cof}(A)$)

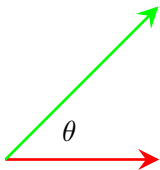
▶ $A^{-1} = \frac{A^*}{|A|}$

Dot Product

- ▶ Also called inner product
 - ▶ $\vec{u} \bullet \vec{v}$ is a scalar
 - ▶ $\vec{u} \bullet \vec{v} = \vec{v} \bullet \vec{u}$
 - ▶ $(a\vec{u}) \bullet \vec{v} = a(\vec{u} \bullet \vec{v})$
 - ▶ $(\vec{u} + \vec{v}) \bullet \vec{w} = \vec{u} \bullet \vec{w} + \vec{v} \bullet \vec{w}$
 - ▶ $\vec{v} \bullet \vec{v} \geq 0$
 - ▶ $\vec{v} \bullet \vec{v} = 0 \leftrightarrow \vec{v} = \vec{0}$
- ▶ Matrix notation: $\vec{u} \bullet \vec{v} = U^T V = u_\alpha v^\alpha$

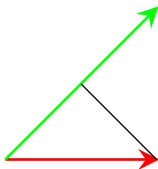
Dot Product as Norm

- ▶ $\vec{v} \bullet \vec{v} = |\vec{v}|^2$
- ▶ $\vec{u} \bullet \vec{v} = |\vec{u}||\vec{v}| \cos \theta$
 - ▶ Defines angle θ !
 - ▶ If $|\vec{v}| = 1$, gives projection of \vec{u} onto \vec{v}
 - ▶ If $|\vec{u}| = |\vec{v}| = 1$, gives just $\cos \theta$



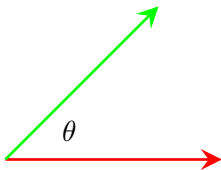
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Orthogonal & Normal

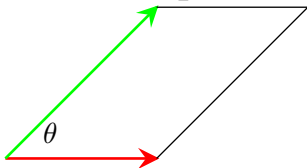
- ▶ *Orthogonal* = perpendicular: $\vec{u} \bullet \vec{v} = 0$
- ▶ *Normal* (this usage) = unit-length: $\vec{u} \bullet \vec{u} = 1$
- ▶ *Orthonormal*: set of vectors both orthogonal and normal
- ▶ *Orthogonal matrix*: rows (& columns) **orthonormal**
 - ▶ For orthogonal matrices, $A^{-1} = A^T$

3D Cross Product

$$\vec{u} \times \vec{v}$$

- ▶ length = area of parallelogram = twice area of triangle
 - ▶ $|\vec{u} \times \vec{v}| = |\vec{u}||\vec{v}|\sin(\theta)$
- ▶ direction = perpendicular to \vec{u} and \vec{v} (right hand rule)

$$\vec{u} \times \vec{v} = \begin{vmatrix} \hat{i} \\ \hat{j} \\ \hat{k} \end{vmatrix} \begin{vmatrix} u^1 & u^2 \\ v^1 & v^2 \end{vmatrix} = \begin{bmatrix} u^1 v^2 - u^2 v^1 \\ u^2 v^0 - u^0 v^2 \\ u^0 v^1 - u^1 v^0 \end{bmatrix}$$



Building an Orthogonal Basis

Vectors \vec{u} , \vec{v} , \vec{w}

- ▶ Gram-Schmidt Orthogonalization (any dimension)

- ▶ $\vec{u}' = \vec{u}$

- ▶ $\vec{v}' = \vec{v} - \hat{u}' (\vec{v} \bullet \hat{u}')$

$$\vec{v}' = \vec{v} - \frac{\vec{u}'}{|\vec{u}'|} \left(\vec{v} \bullet \frac{\vec{u}'}{|\vec{u}'|} \right)$$

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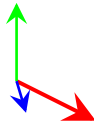
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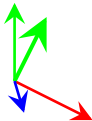
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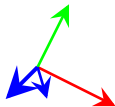
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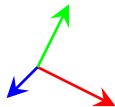
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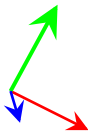
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