

# CMSC 313 Lecture 24

- **State Assignment Heuristics**
- **Using J-K Flip-Flops**

# Last Time

- **Mealy vs Moore finite state machines**
- **Vending machine example**
- **Sequence detector example**
- **State reduction algorithm**

# Simplifying Finite State Machines

- **State Reduction: equivalent FSM with fewer states**
- **State Assignment: choose an assignment of bit patterns to states (e.g., B is 010) that results in a smaller circuit**
- **Choice of flip-flops: use D flip-flops, J-K flip-flops or a T flip-flops? a good choice could lead to simpler circuits.**

# The State Assignment Problem

- Two state assignments for machine  $M_2$ .

P.S. \ Input	X	
	0	1
A	B/1	A/1
B	C/0	D/1
C	C/0	D/0
D	B/1	A/0

Machine  $M_2$ 

Input \ $S_0S_1$	X	
	0	1
A: 00	01/1	00/1
B: 01	10/0	11/1
C: 10	10/0	11/0
D: 11	01/1	00/0

State assignment  $SA_0$ 

Input \ $S_0S_1$	X	
	0	1
A: 00	01/1	00/1
B: 01	11/0	10/1
C: 11	11/0	10/0
D: 10	01/1	00/0

State assignment  $SA_1$

# State Assignment SA<sub>0</sub>

- Boolean equations for machine  $M_2$  using state assignment SA<sub>0</sub>.

		$X$	
		0	1
$S_0S_1$	00		
	01	1	1
	11		
	10	1	1

$$S_0 = \bar{S}_0S_1 + S_0\bar{S}_1$$

		$X$	
		0	1
$S_0S_1$	00	1	
	01		1
	11	1	
	10		1

$$S_1 = \bar{S}_0\bar{S}_1\bar{X} + \bar{S}_0S_1X + S_0S_1\bar{X} + S_0\bar{S}_1X$$

		$X$	
		0	1
$S_0S_1$	00	1	1
	01		1
	11	1	
	10		

$$Z = \bar{S}_0\bar{S}_1 + \bar{S}_0X + S_0S_1\bar{X}$$

# State Assignment SA<sub>1</sub>

- Boolean equations for machine  $M_2$  using state assignment SA<sub>1</sub>.

		X	
		0	1
S <sub>0</sub> S <sub>1</sub>	00		
	01	1	1
	11	1	1
	10		

$$S_0 = S_1$$

		X	
		0	1
S <sub>0</sub> S <sub>1</sub>	00	1	
	01	1	
	11	1	
	10	1	

$$S_1 = \bar{X}$$

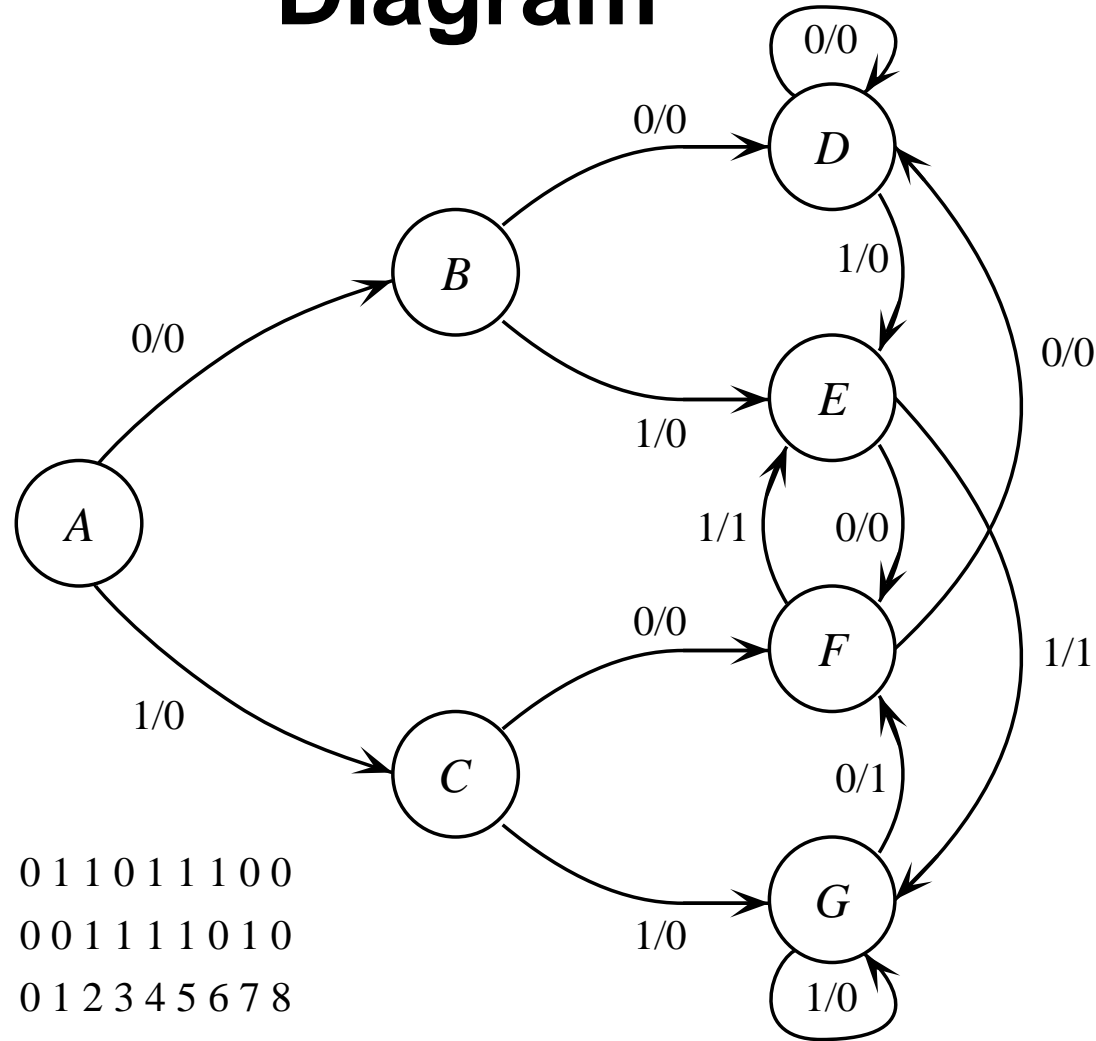
		X	
		0	1
S <sub>0</sub> S <sub>1</sub>	00	1	1
	01		1
	11		
	10	1	

$$Z = \bar{S}_1\bar{X} + \bar{S}_0X$$

# State Assignment Heuristics

- **No known efficient alg. for best state assignment**
- **Some heuristics (rules of thumb):**
  - ◇ **The initial state should be simple to reset — all zeroes or all ones.**
  - ◇ **Minimize the number of state variables that change on each transition.**
  - ◇ **Maximize the number of state variables that don't change on each transition.**
  - ◇ **Exploit symmetries in the state diagram.**
  - ◇ **If there are unused states (when the number of states  $s$  is not a power of 2), choose the unused state variable combinations carefully. (Don't just use the first  $s$  combination of state variables.)**
  - ◇ **Decompose the set of state variables into bits or fields that have well-defined meaning with respect to the input or output behavior.**
  - ◇ **Consider using more than the minimum number of states to achieve the objectives above.**

# Sequence Detector State Transition Diagram



Input: 0 1 1 0 1 1 1 0 0  
 Output: 0 0 1 1 1 1 0 1 0  
 Time: 0 1 2 3 4 5 6 7 8



# Sequence Detector State Table

Present state \ Input	X	
	0	1
<i>A</i>	<i>B</i> /0	<i>C</i> /0
<i>B</i>	<i>D</i> /0	<i>E</i> /0
<i>C</i>	<i>F</i> /0	<i>G</i> /0
<i>D</i>	<i>D</i> /0	<i>E</i> /0
<i>E</i>	<i>F</i> /0	<i>G</i> /1
<i>F</i>	<i>D</i> /0	<i>E</i> /1
<i>G</i>	<i>F</i> /1	<i>G</i> /0

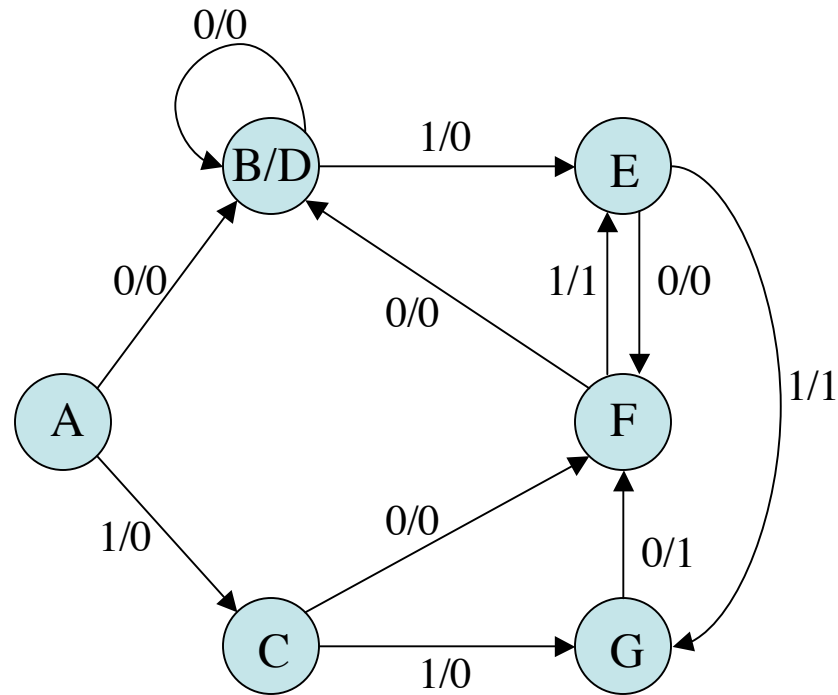
# Sequence Detector State Reduction Table

	A	B	C	D	E	F	G
A	X	x	x	x	x	x	x
B	X	X	x		x	x	x
C	X	X	X	x	x	x	x
D	X	X	X	X	x	x	x
E	X	X	X	X	X	x	x
F	X	X	X	X	X	X	x
G	X	X	X	X	X	X	X

# Sequence Detector Reduced State Table

Present state \ Input	X	
	0	1
A: A'	B'/0	C'/0
BD: B'	B'/0	D'/0
C: C'	E'/0	F'/0
E: D'	E'/0	F'/1
F: E'	B'/0	D'/1
G: F'	E'/1	F'/0

## 6-State Sequence Detector



# Sequence Detector State Assignment

Present state \ Input	X	
	0	1
$S_2S_1S_0$	$S_2S_1S_0Z$	$S_2S_1S_0Z$
$A': 000$	001/0	010/0
$B': 001$	001/0	011/0
$C': 010$	100/0	101/0
$D': 011$	100/0	101/1
$E': 100$	001/0	011/1
$F': 101$	100/1	101/0

# Sequence Detector K-Maps

- K-map reduction of next state and output functions for sequence detector.

	$S_2S_1$	00	01	11	10
$S_0X$	00	1		$d$	1
	01		1	$d$	1
	11	1	1	$d$	1
	10	1		$d$	

$$S_0 = \bar{S}_2\bar{S}_1\bar{X} + S_0X + S_2\bar{S}_0 + S_1X$$

	$S_2S_1$	00	01	11	10
$S_0X$	00			$d$	
	01	1		$d$	1
	11	1		$d$	
	10			$d$	

$$S_1 = \bar{S}_2\bar{S}_1X + S_2\bar{S}_0X$$

	$S_2S_1$	00	01	11	10
$S_0X$	00		1	$d$	
	01		1	$d$	
	11		1	$d$	1
	10		1	$d$	1

$$S_2 = S_2S_0 + S_1$$

	$S_2S_1$	00	01	11	10
$S_0X$	00			$d$	
	01			$d$	1
	11		1	$d$	
	10			$d$	1

$$Z = S_2\bar{S}_0X + S_1S_0X + S_2S_0\bar{X}$$

# Improved Sequence Detector?

- **Formulas from the 7-state FSM:**

$$s2' = (\overline{s0} + x) (s2 + s1 + s0)$$

$$s1' = \overline{s0} x + s0 \overline{x} = s0 \text{ xor } x$$

$$s0' = \overline{x}$$

$$z = s2 \overline{s1} x + s2 s1 \overline{x}$$

- **Formulas from the 6-state FSM:**

$$s2' = s2 s0 + s1$$

$$s1' = \overline{s2} \overline{s1} x + s2 \overline{s0} x$$

$$s0' = \overline{s2} \overline{s1} \overline{x} + s0 x + s2 \overline{s0} + s1 x$$

$$z = s2 \overline{s0} x + s1 s0 x + s2 s0 \overline{x}$$

# Sequence Detector State Assignment

## 7-state

	s2	s1	s0	x	s2'	s1'	s0'	z
0	0	0	0	0	0	0	1	0
1	0	0	0	1	0	1	0	0
2	0	0	1	0	0	1	1	0
3	0	0	1	1	1	0	0	0
4	0	1	0	0	1	0	1	0
5	0	1	0	1	1	1	0	0
6	0	1	1	0	0	1	1	0
7	0	1	1	1	1	0	0	0
8	1	0	0	0	1	0	1	0
9	1	0	0	1	1	1	0	1
10	1	0	1	0	0	1	1	0
11	1	0	1	1	1	0	0	1
12	1	1	0	0	1	0	1	1
13	1	1	0	1	1	1	0	0
14	1	1	1	0	d	d	d	d
15	1	1	1	1	d	d	d	d

## new 6-state

	s2	s1	s0	x	s2'	s1'	s0'	z
0	0	0	0	0	0	0	1	0
1	0	0	0	1	0	1	0	0
2	0	0	1	0	0	0	1	0
3	0	0	1	1	1	0	0	0
4	0	1	0	0	1	0	1	0
5	0	1	0	1	1	1	0	0
6	0	1	1	0	d	d	d	d
7	0	1	1	1	d	d	d	d
8	1	0	0	0	1	0	1	0
9	1	0	0	1	1	1	0	1
10	1	0	1	0	0	0	1	0
11	1	0	1	1	1	0	0	1
12	1	1	0	0	1	0	1	1
13	1	1	0	1	1	1	0	0
14	1	1	1	0	d	d	d	d
15	1	1	1	1	d	d	d	d

A = 000  
 B = 001  
 C = 010  
 D = 011

E = 100  
 F = 101  
 G = 110

A = 000  
 B/D = 001  
 C = 010  
~~D = 011~~

E = 100  
 F = 101  
 G = 110



# 6-State Sequence Detector

7-state

s0 x		s2 s1		s2	
		00	01	11	10
00	0	0	1	1	1
01	0	1	1	1	
11	1	1	d	1	
10	0	0	d	0	

s1

$$s2' = (\overline{s0} + x)(s2 + s1 + s0)$$

new 6-state

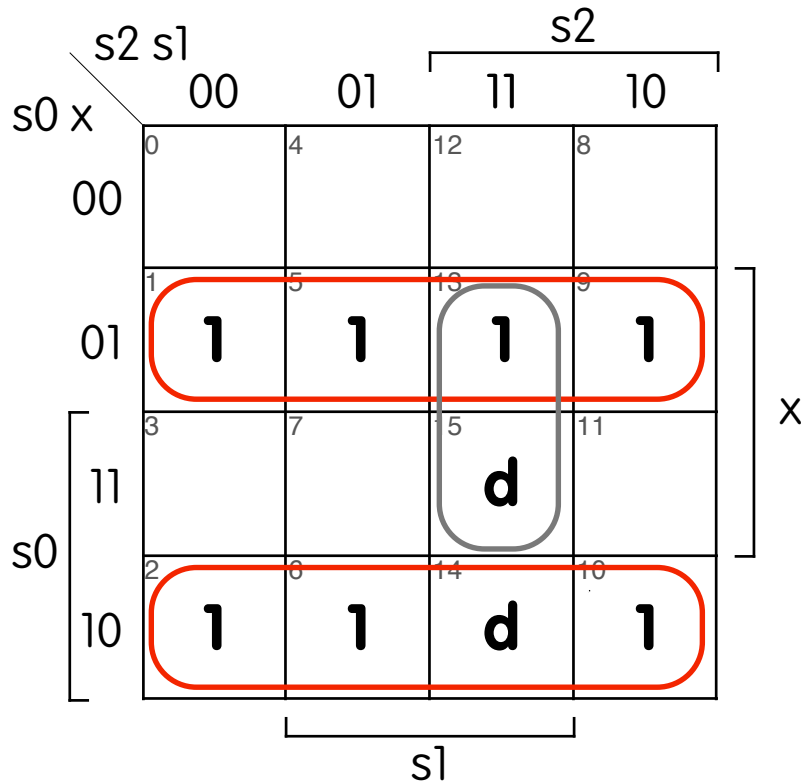
s0 x		s2 s1		s2	
		00	01	11	10
00	0	1	1	1	
01	0	1	1	1	
11	1	d	d	1	
10	0	d	d	0	

s1

$$s2' = (\overline{s0} + x)(s2 + s1 + s0)$$

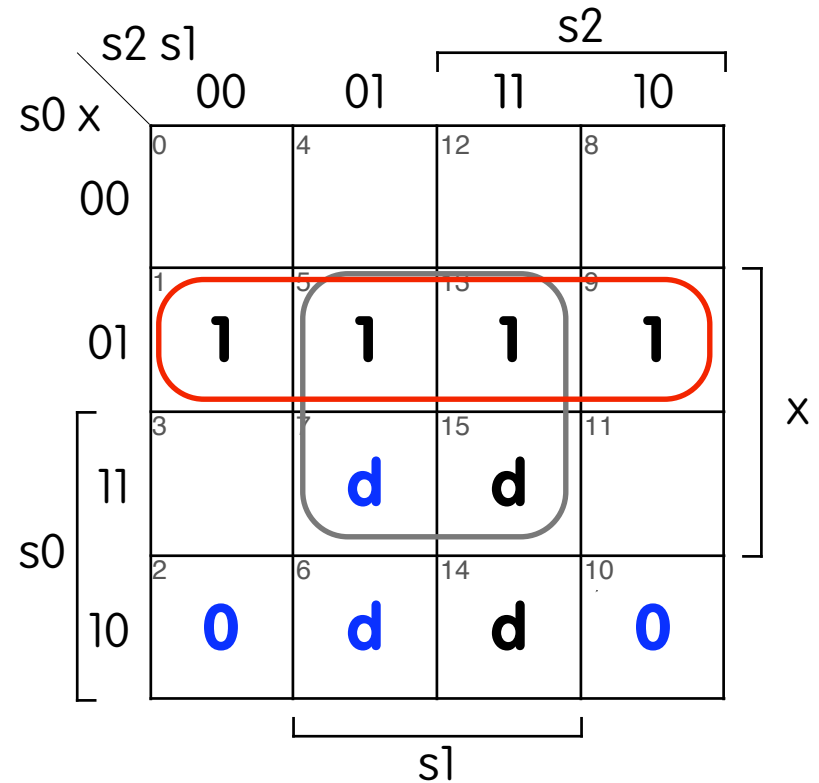
# 6-State Sequence Detector

7-state



$$s1' = \overline{s0} x + s0 \overline{x}$$

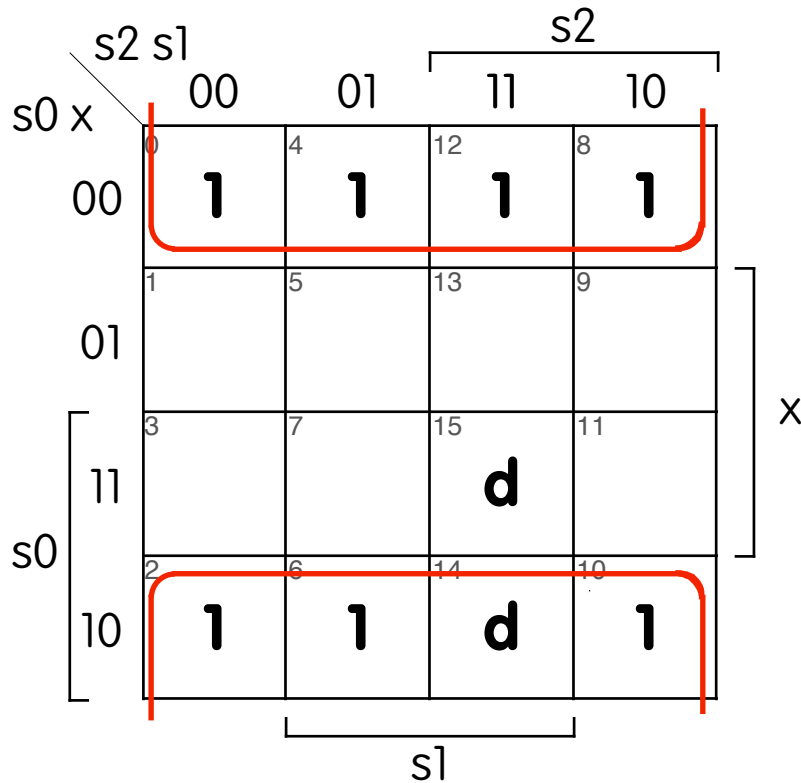
new 6-state



$$s1' = \overline{s0} x$$

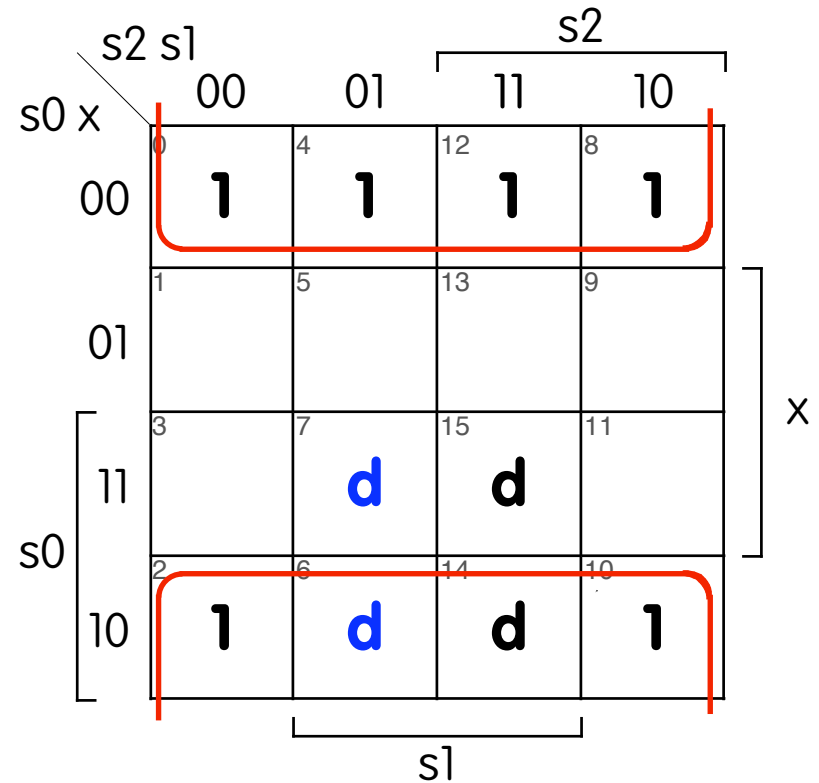
# 6-State Sequence Detector

7-state



$$s0' = \bar{x}$$

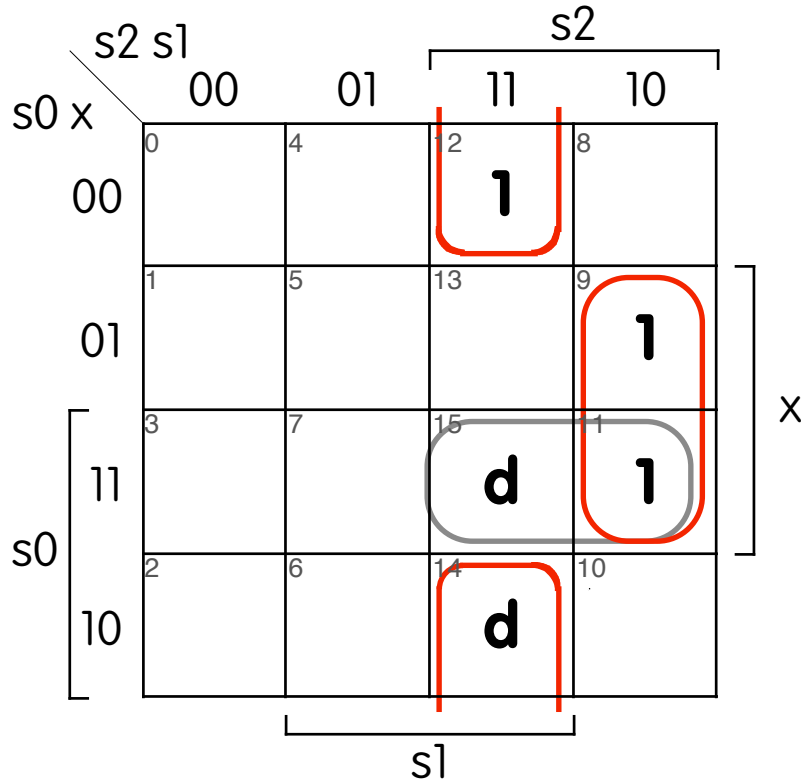
new 6-state



$$s0' = \bar{x}$$

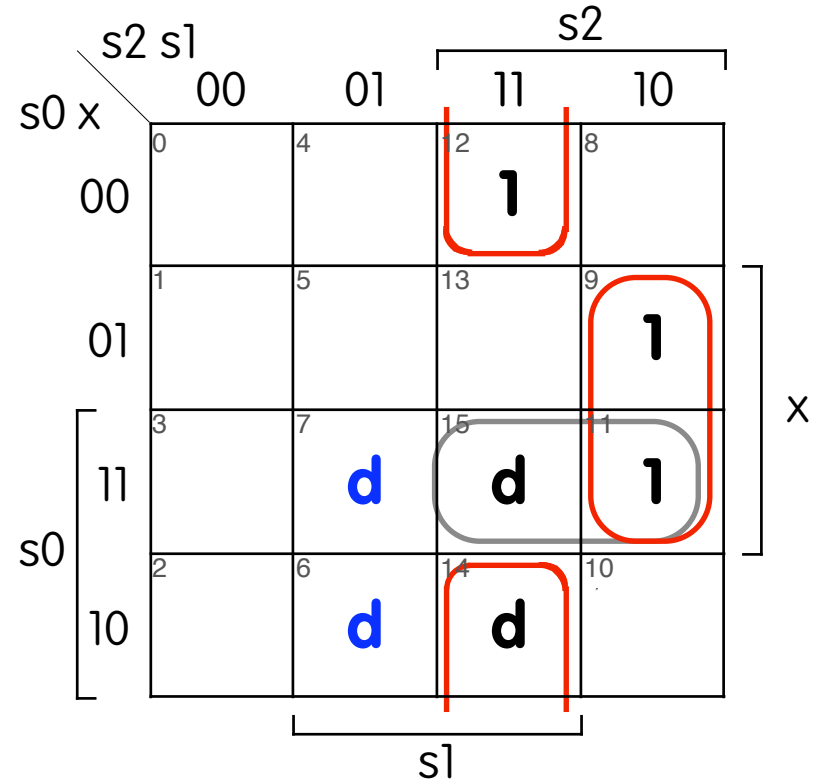
# 6-State Sequence Detector

7-state



$$z = s_2 \overline{s_1} x + s_2 s_1 \overline{x}$$

new 6-state



$$z = s_2 \overline{s_1} x + s_2 s_1 \overline{x}$$

# Improved Sequence Detector

- **Textbook formulas for the 6-state FSM:**

$$s2' = s2 s0 + s1$$

$$s1' = \overline{s2} \overline{s1} x + s2 \overline{s0} x$$

$$s0' = \overline{s2} \overline{s1} \overline{x} + s0 x + s2 \overline{s0} + s1 x$$

$$z = s2 \overline{s0} x + s1 s0 x + s2 s0 \overline{x}$$

- **New formulas for the 6-state FSM:**

$$s2' = (\overline{s0} + x) (s2 + s1 + s0)$$

$$s1' = \overline{s0} x$$

$$s0' = \overline{x}$$

$$z = s2 \overline{s1} x + s2 s1 \overline{x}$$

# Excitation Tables

- Each table shows the settings that must be applied at the inputs at time  $t$  in order to change the outputs at time  $t+1$ .

*S-R  
flip-flop*

$Q_t$	$Q_{t+1}$	$S$	$R$
0	0	0	0
0	1	1	0
1	0	0	1
1	1	0	0

*D  
flip-flop*

$Q_t$	$Q_{t+1}$	$D$
0	0	0
0	1	1
1	0	0
1	1	1

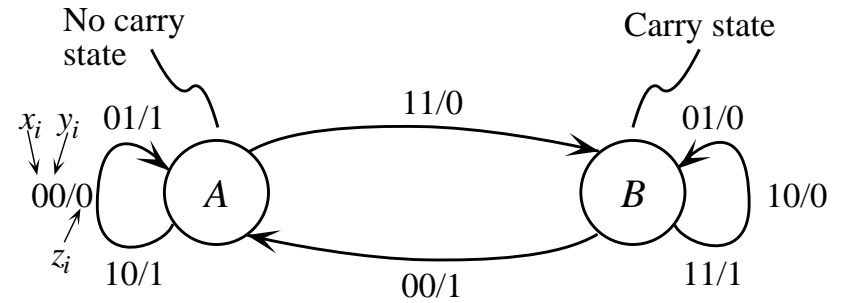
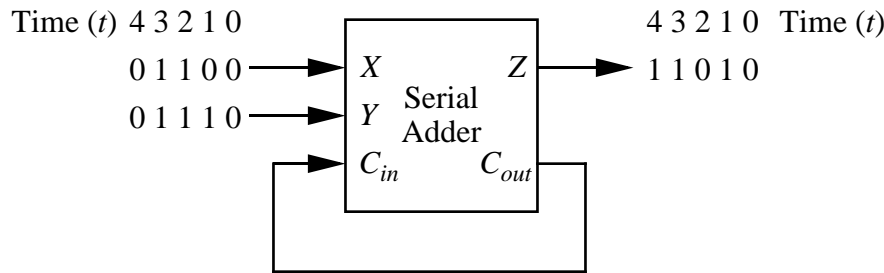
*J-K  
flip-flop*

$Q_t$	$Q_{t+1}$	$J$	$K$
0	0	0	$d$
0	1	1	$d$
1	0	$d$	1
1	1	$d$	0

*T  
flip-flop*

$Q_t$	$Q_{t+1}$	$T$
0	0	0
0	1	1
1	0	1
1	1	0

# Serial Adder



- **State transition diagram, state table, and state assignment for a serial adder.**

	Input	XY			
Present state		00	01	10	11
A		A/0	A/1	A/1	B/0
B		A/1	B/0	B/0	B/1

Next state      Output

	Input	XY			
Present state ( $S_i$ )		00	01	10	11
A:0		0/0	0/1	0/1	1/0
B:1		0/1	1/0	1/0	1/1

# Serial Adder Next-State Functions

- Truth table showing next-state functions for a serial adder for D, S-R, T, and J-K flip-flops. Shaded functions are used in the example.

Present State			(Set) (Reset)						
<i>X</i>	<i>Y</i>	<i>S<sub>t</sub></i>	<i>D</i>	<i>S</i>	<i>R</i>	<i>T</i>	<i>J</i>	<i>K</i>	<i>Z</i>
0	0	0	0	0	0	0	0	<i>d</i>	0
0	0	1	0	0	1	1	<i>d</i>	1	1
0	1	0	0	0	0	0	0	<i>d</i>	1
0	1	1	1	0	0	0	<i>d</i>	0	0
1	0	0	0	0	0	0	0	<i>d</i>	1
1	0	1	1	0	0	0	<i>d</i>	0	0
1	1	0	1	1	0	1	1	<i>d</i>	0
1	1	1	1	0	0	0	<i>d</i>	0	1

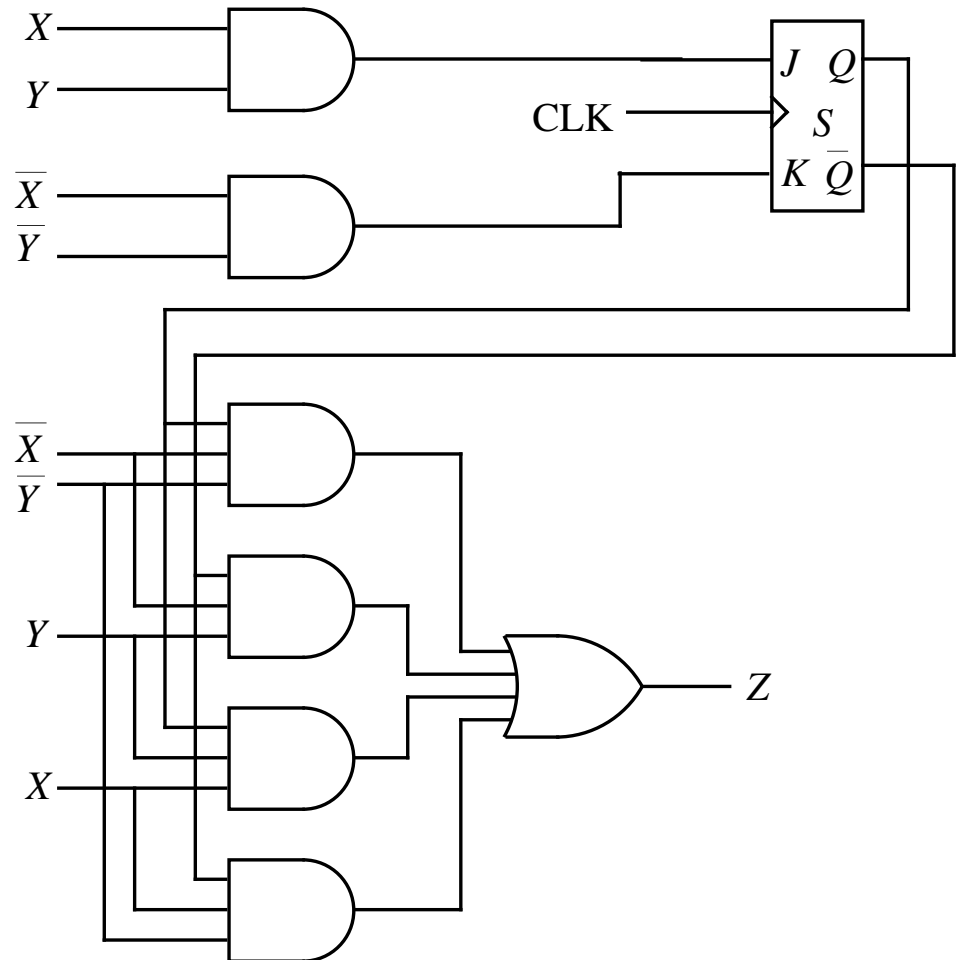


# J-K Flip-Flop Serial Adder Circuit

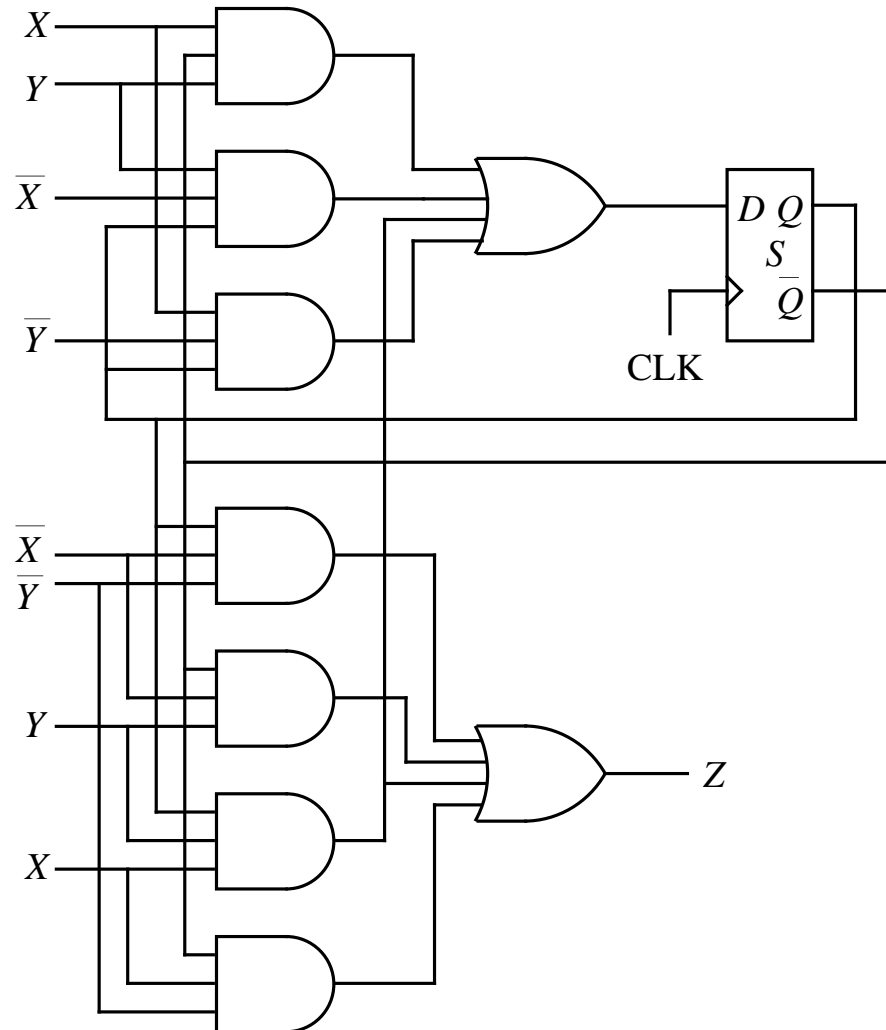
$$J = XY$$

$$K = \bar{X}\bar{Y}$$

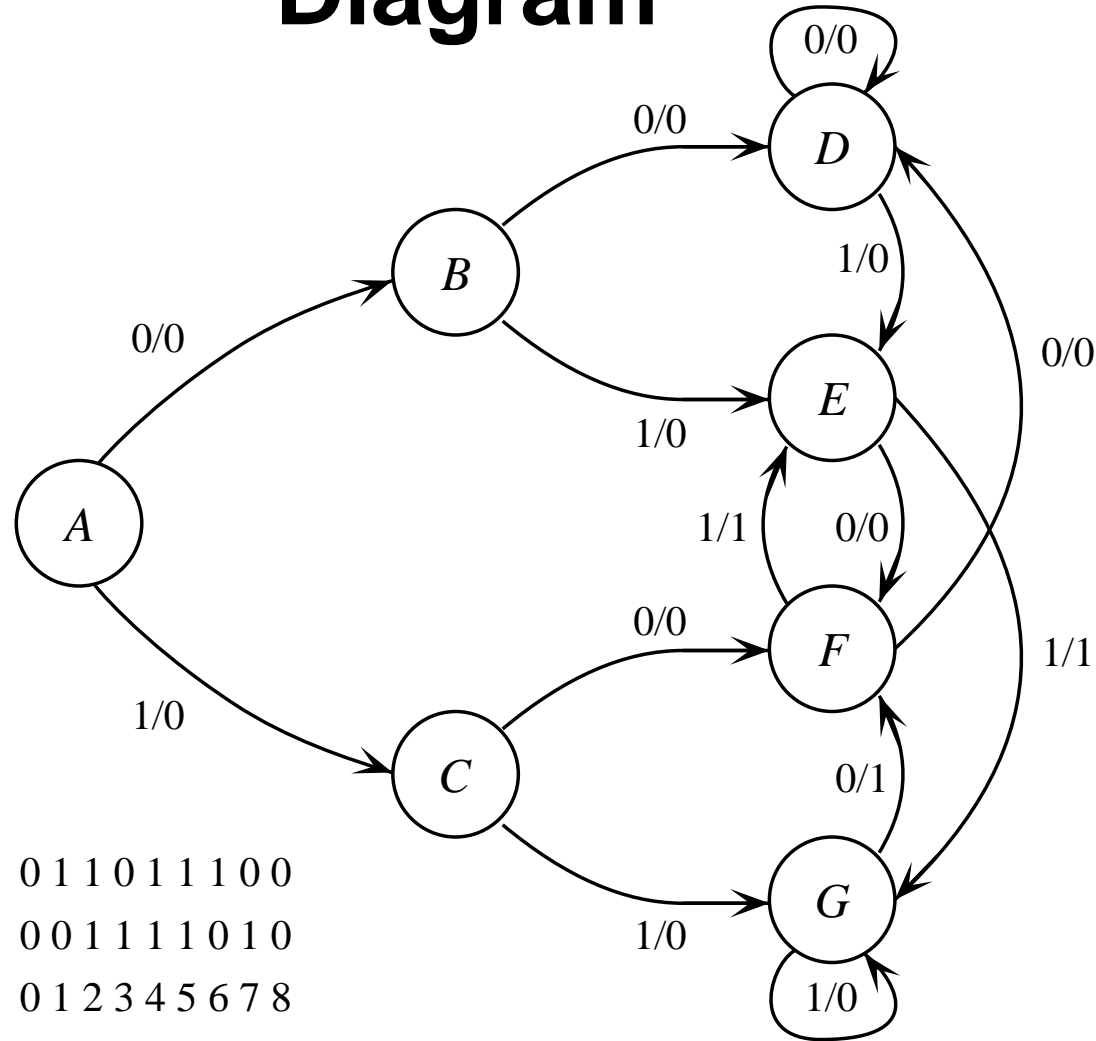
$$Z = \bar{X}\bar{Y}S + \bar{X}Y\bar{S} + XY\bar{S} + X\bar{Y}S$$



# D Flip-Flop Serial Adder Circuit

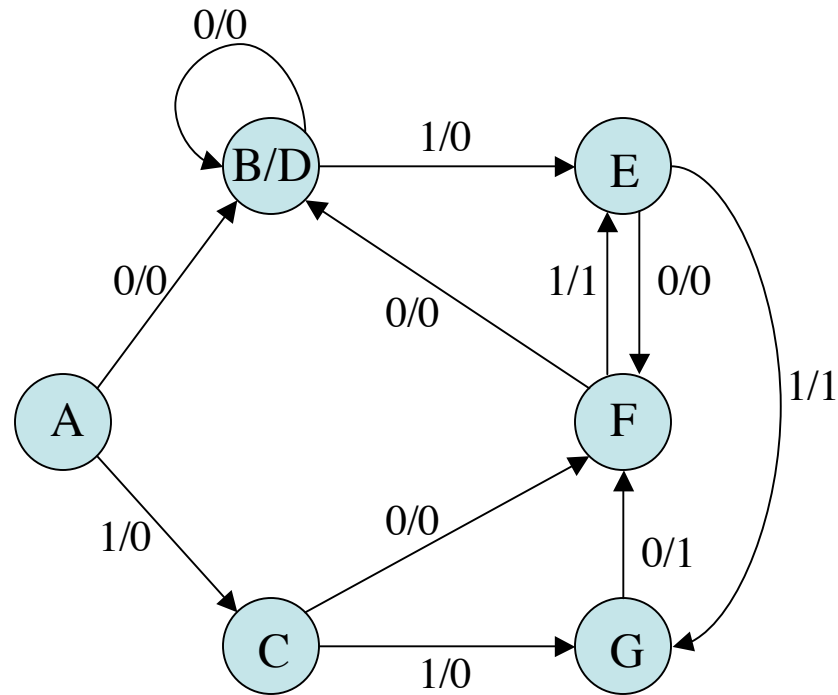


# Sequence Detector State Transition Diagram



Input: 0 1 1 0 1 1 1 0 0  
 Output: 0 0 1 1 1 1 0 1 0  
 Time: 0 1 2 3 4 5 6 7 8

## 6-State Sequence Detector



# Improved Sequence Detector?

- **Formulas from the 7-state FSM:**

$$s2' = (\overline{s0} + x) (s2 + s1 + s0)$$

$$s1' = \overline{s0} x + s0 \overline{x} = s0 \text{ xor } x$$

$$s0' = \overline{x}$$

$$z = s2 \overline{s1} x + s2 s1 \overline{x}$$

- **Formulas from the 6-state FSM:**

$$s2' = s2 s0 + s1$$

$$s1' = \overline{s2} \overline{s1} x + s2 \overline{s0} x$$

$$s0' = \overline{s2} \overline{s1} \overline{x} + s0 x + s2 \overline{s0} + s1 x$$

$$z = s2 \overline{s0} x + s1 s0 x + s2 s0 \overline{x}$$

# Sequence Detector State Assignment

## 7-state

	s2	s1	s0	x	s2'	s1'	s0'	z
0	0	0	0	0	0	0	1	0
1	0	0	0	1	0	1	0	0
2	0	0	1	0	0	1	1	0
3	0	0	1	1	1	0	0	0
4	0	1	0	0	1	0	1	0
5	0	1	0	1	1	1	0	0
6	0	1	1	0	0	1	1	0
7	0	1	1	1	1	0	0	0
8	1	0	0	0	1	0	1	0
9	1	0	0	1	1	1	0	1
10	1	0	1	0	0	1	1	0
11	1	0	1	1	1	0	0	1
12	1	1	0	0	1	0	1	1
13	1	1	0	1	1	1	0	0
14	1	1	1	0	d	d	d	d
15	1	1	1	1	d	d	d	d

## new 6-state

	s2	s1	s0	x	s2'	s1'	s0'	z
0	0	0	0	0	0	0	1	0
1	0	0	0	1	0	1	0	0
2	0	0	1	0	0	0	1	0
3	0	0	1	1	1	0	0	0
4	0	1	0	0	1	0	1	0
5	0	1	0	1	1	1	0	0
6	0	1	1	0	d	d	d	d
7	0	1	1	1	d	d	d	d
8	1	0	0	0	1	0	1	0
9	1	0	0	1	1	1	0	1
10	1	0	1	0	0	0	1	0
11	1	0	1	1	1	0	0	1
12	1	1	0	0	1	0	1	1
13	1	1	0	1	1	1	0	0
14	1	1	1	0	d	d	d	d
15	1	1	1	1	d	d	d	d

A = 000  
 B = 001  
 C = 010  
 D = 011

E = 100  
 F = 101  
 G = 110

A = 000  
 B/D = 001  
 C = 010  
~~D = 011~~

E = 100  
 F = 101  
 G = 110

# Improved Sequence Detector

- **Textbook formulas for the 6-state FSM:**

$$s2' = s2 s0 + s1$$

$$s1' = \overline{s2} \overline{s1} x + s2 \overline{s0} x$$

$$s0' = \overline{s2} \overline{s1} \overline{x} + s0 x + s2 \overline{s0} + s1 x$$

$$z = s2 \overline{s0} x + s1 s0 x + s2 s0 \overline{x}$$

- **New formulas for the 6-state FSM:**

$$s2' = (\overline{s0} + x) (s2 + s1 + s0)$$

$$s1' = \overline{s0} x$$

$$s0' = \overline{x}$$

$$z = s2 \overline{s1} x + s2 s1 \overline{x}$$

# 6-State Sequence Detector

	s2	s1	s0	x	s2'	s1'	s0'	z	j2	k2	j1	k1	j0	k0
0	0	0	0	0	0	0	1	0	0	<i>d</i>	0	<i>d</i>	1	<i>d</i>
1	0	0	0	1	0	1	0	0	0	<i>d</i>	1	<i>d</i>	0	<i>d</i>
2	0	0	1	0	0	0	1	0	0	<i>d</i>	0	<i>d</i>	<i>d</i>	0
3	0	0	1	1	1	0	0	0	1	<i>d</i>	0	<i>d</i>	<i>d</i>	1
4	0	1	0	0	1	0	1	0	1	<i>d</i>	<i>d</i>	1	1	<i>d</i>
5	0	1	0	1	1	1	0	0	1	<i>d</i>	<i>d</i>	0	0	<i>d</i>
6	0	1	1	0	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>
7	0	1	1	1	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>
8	1	0	0	0	1	0	1	0	<i>d</i>	0	0	<i>d</i>	1	<i>d</i>
9	1	0	0	1	1	1	0	1	<i>d</i>	0	1	<i>d</i>	0	<i>d</i>
10	1	0	1	0	0	0	1	0	<i>d</i>	1	0	<i>d</i>	<i>d</i>	0
11	1	0	1	1	1	0	0	1	<i>d</i>	0	0	<i>d</i>	<i>d</i>	1
12	1	1	0	0	1	0	1	1	<i>d</i>	0	<i>d</i>	1	1	<i>d</i>
13	1	1	0	1	1	1	0	0	<i>d</i>	0	<i>d</i>	0	0	<i>d</i>
14	1	1	1	0	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>
15	1	1	1	1	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>	<i>d</i>

Q	Q'	J	K
0	0	0	<i>d</i>
0	1	1	<i>d</i>
1	0	<i>d</i>	1
1	1	<i>d</i>	0



# 6-State Sequence Detector

**J2**

s0 x		s2 s1		s2		
		00	01	11	10	
0	4	12	8	x		
00	<b>0</b>	<b>1</b>	<b>d</b>			<b>d</b>
1	5	13	9			
01	<b>0</b>	<b>1</b>	<b>d</b>			<b>d</b>
3	7	15	11	x		
11	<b>1</b>	<b>d</b>	<b>d</b>			<b>d</b>
2	6	14	10			
10	<b>0</b>	<b>d</b>	<b>d</b>			<b>d</b>
		s1				

$$J2 = s1 + s0 x$$

**K2**

s0 x		s2 s1		s2		
		00	01	11	10	
0	4	12	8	x		
00	<b>d</b>	<b>d</b>	<b>0</b>			<b>0</b>
1	5	13	9			
01	<b>d</b>	<b>d</b>	<b>0</b>			<b>0</b>
3	7	15	11	x		
11	<b>d</b>	<b>d</b>	<b>d</b>			<b>0</b>
2	6	14	10			
10	<b>d</b>	<b>d</b>	<b>d</b>			<b>1</b>
		s1				

$$K2 = s0 \bar{x}$$

# 6-State Sequence Detector

**J1**

		s2 s1		s2	
		00	01	11	10
s0 x	00	0 <b>0</b>	4 <b>d</b>	12 <b>d</b>	8 <b>0</b>
	01	1 <b>1</b>	5 <b>d</b>	13 <b>d</b>	9 <b>1</b>
s0	11	3 <b>0</b>	7 <b>d</b>	15 <b>d</b>	11 <b>0</b>
	10	2 <b>0</b>	6 <b>d</b>	14 <b>d</b>	10 <b>0</b>

s1

$$J1 = \overline{s0} x$$

**K1**

		s2 s1		s2	
		00	01	11	10
s0 x	00	0 <b>d</b>	4 <b>1</b>	12 <b>1</b>	8 <b>d</b>
	01	1 <b>d</b>	5 <b>0</b>	13 <b>0</b>	9 <b>d</b>
s0	11	3 <b>d</b>	7 <b>d</b>	15 <b>d</b>	11 <b>d</b>
	10	2 <b>d</b>	6 <b>d</b>	14 <b>d</b>	10 <b>d</b>

s1

$$K1 = \overline{x}$$

# 6-State Sequence Detector

**J0**

		s2 s1		s2		
	s0 x	00	01	11	10	
	00	0	4	12	8	
	01	1	5	13	9	x
	11	3	7	15	11	
	10	2	6	14	10	
		s1				
		00	01	11	10	
	00	1	1	1	1	
	01	0	0	0	0	
	11	d	d	d	d	
	10	d	d	d	d	

$$J0 = \overline{x}$$

**K0**

		s2 s1		s2		
	s0 x	00	01	11	10	
	00	0	4	12	8	
	01	1	5	13	9	x
	11	3	7	15	11	
	10	2	6	14	10	
		s1				
		00	01	11	10	
	00	d	d	d	d	
	01	d	d	d	d	
	11	1	d	d	1	
	10	0	d	d	0	

$$K0 = x$$

# Improved Sequence Detector

- **Formulas for the 6-state FSM with D Flip-flops:**

$$s2' = (\overline{s0} + x) (s2 + s1 + s0)$$

$$s1' = \overline{s0} x$$

$$s0' = \overline{x}$$

- **Formulas for the 6-state FSM with J-K Flip-flops:**

$$J2 = s1 + s0 x \quad K2 = s0 \overline{x}$$

$$J1 = \overline{s0} x \quad K1 = \overline{x}$$

$$J0 = \overline{x} \quad K0 = x$$

**Due: Tuesday, December 7, 2003**

1. (10 points) Question A.13, page 494, Murdocca & Heuring
2. (10 points) Question A.29, page 497, Murdocca & Heuring
3. (10 points) Question B.10, page 542, Murdocca & Heuring
4. (10 points) Question B.11, page 542, Murdocca & Heuring
5. (60 points) This problem asks you to take the steps involved in the design process of a finite state machine. You will design a finite state machine that has a one bit input  $x$  and a one bit output  $z$ . The machine must output 1 for every input sequence ending in the string 0010 or 100. The output should be 0 in all other cases.

[Adapted from *Contemporary Logic Design*, Randy H. Katz, Benjamin/Cummings Publishing, 1994.]

- (a) (10 points) In the space provided on the next page, draw the minimum state-transition diagram for the finite state machine described above. You must use the state-minimization algorithm described in class to show that the finite state machine has the minimum number of states. (*Hint*: You should have fewer than 8 states in your machine.)
- (b) (5 points) Use the state assignment heuristics described in class and pick *two* different state assignments for your finite state machine. *Note*: the bit pattern for the initial state must be 000.
- (c) (40 points) For each of the two state assignments:
  - i. Fill in the truth tables with values for D flip-flops, for the output bit and for J-K flip-flops.
  - ii. Use the Karnaugh maps provided to minimize the formulas for each column of the truth table.
  - iii. Count the number of gates needed for each implementation.
- (d) (5 points) Should you use your first or second state assignment? D flip-flops or J-K flip-flops?

*Note*: Keep a copy of your work for the last question. You will need it for DigSim Assignment 3.

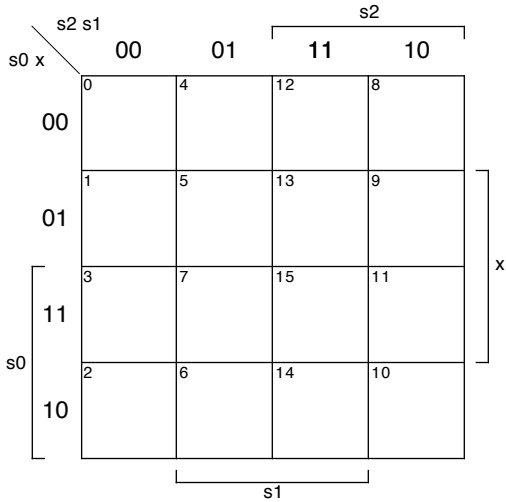
**Minimized State Transition Diagram (show work)**

**State Assignment:**

	Assignment #1	Assignment#2
A	000	000
B		
C		
D		
E		
F		
unused		
unused		

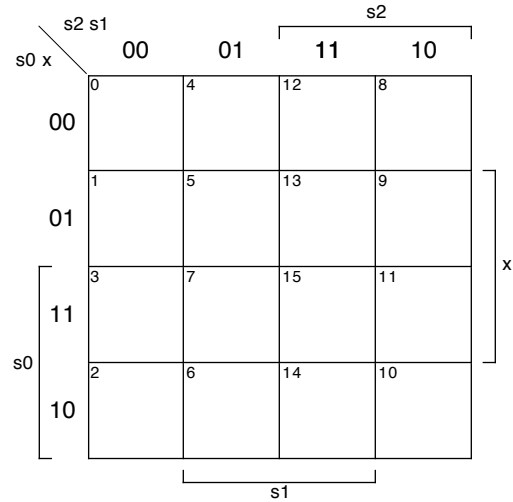


# Assignment #1: Karnaugh Maps for D Flip-Flops and the output



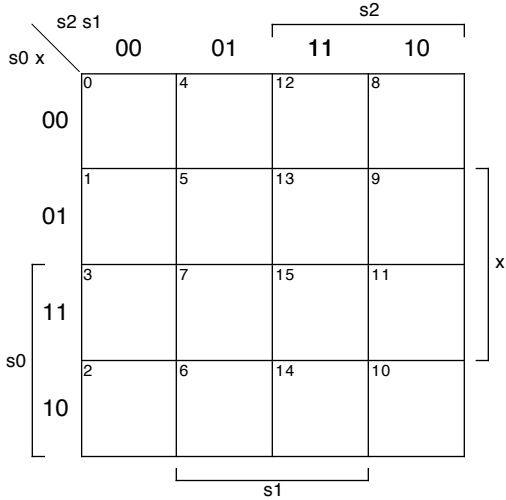
$s2' =$

# of gates =



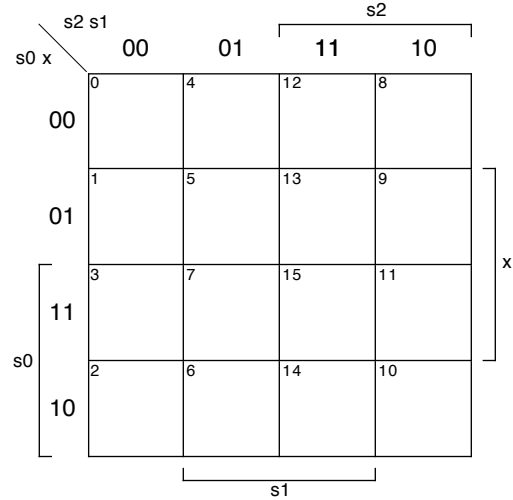
$s1' =$

# of gates =



$s0' =$

# of gates =



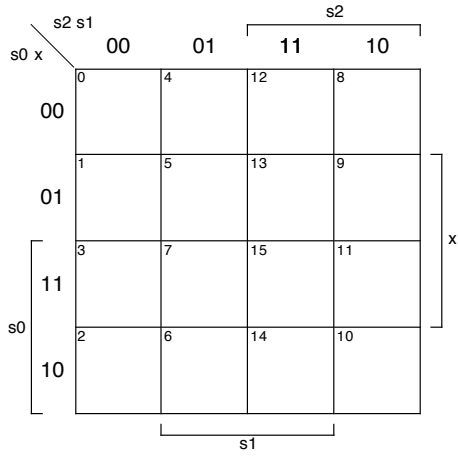
$z =$

# of gates =

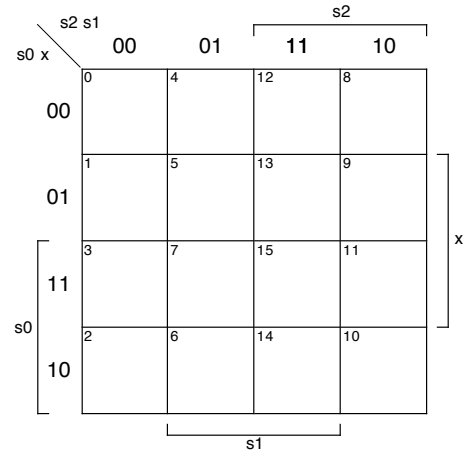
Total # of gates for D flip-flops (don't count z) =



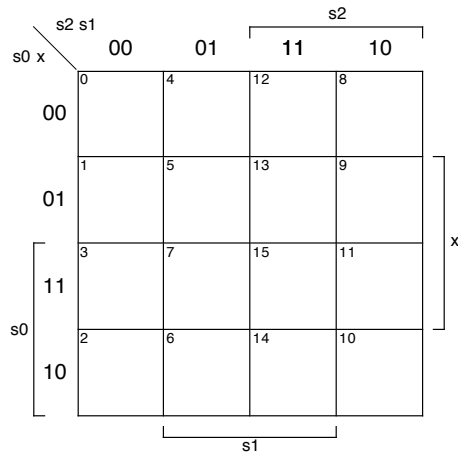
# Assignment #1: Karnaugh Maps for J-K Flip-Flops



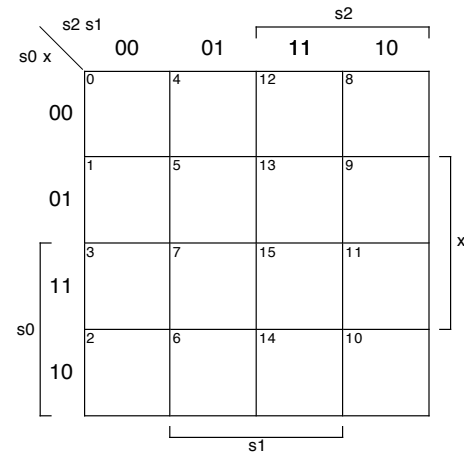
j2 =  
# of gates =



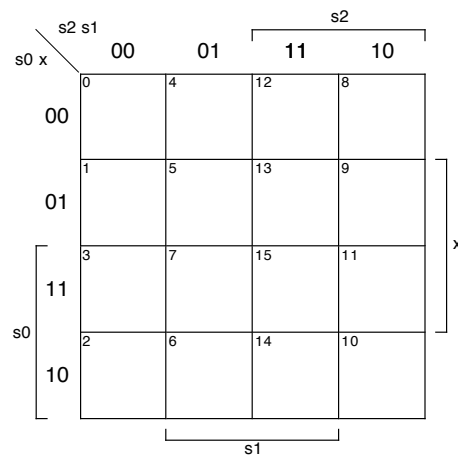
k2 =  
# of gates =



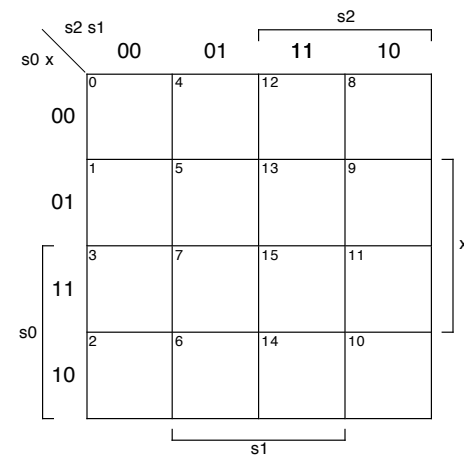
j1 =  
# of gates =



k1 =  
# of gates =



j0 =  
# of gates =

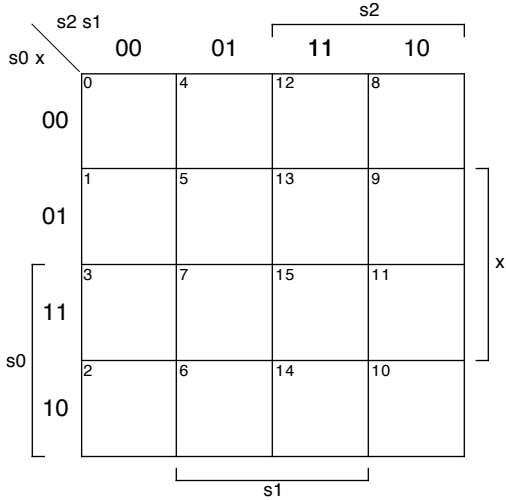


k0 =  
# of gates =

Total # of gates for J-K flip-flops (don't count z) =

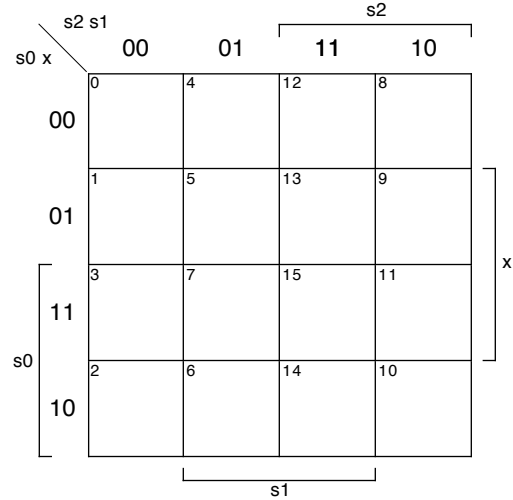


## Assignment #2: Karnaugh Maps for D Flip-Flops and the output



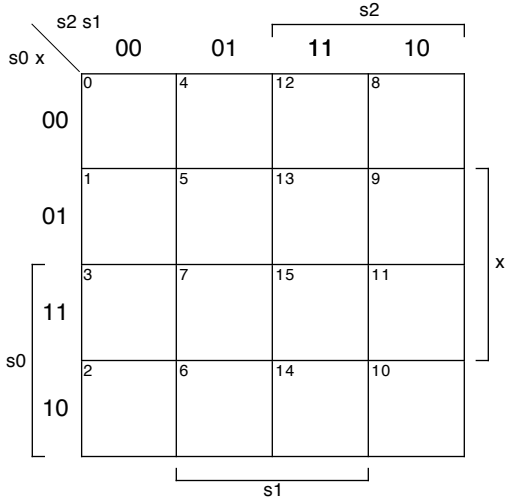
$s2' =$

# of gates =



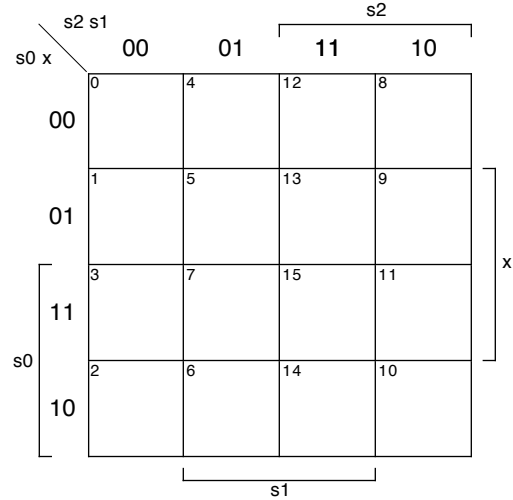
$s1' =$

# of gates =



$s0' =$

# of gates =

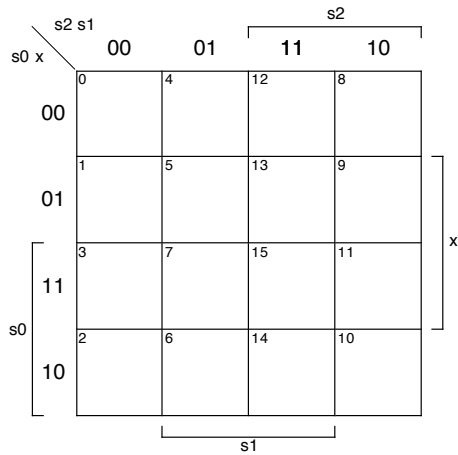


$z =$

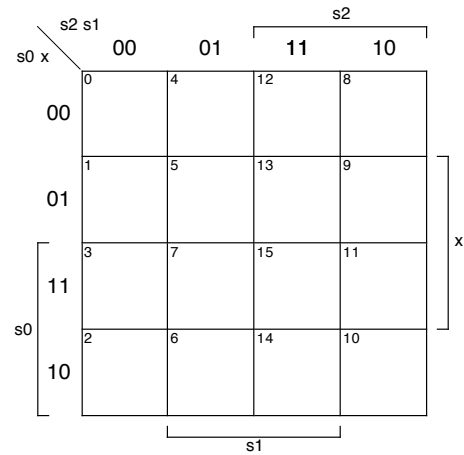
# of gates =

Total # of gates for D flip-flops (don't count z) =

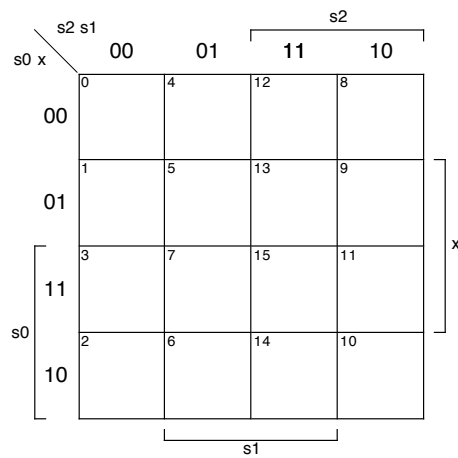
## Assignment #2: Karnaugh Maps for J-K Flip-Flops



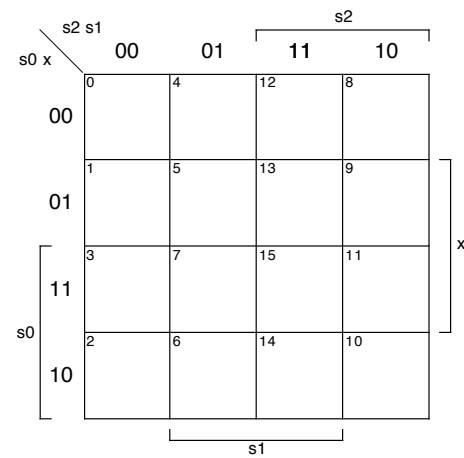
j2 =  
# of gates =



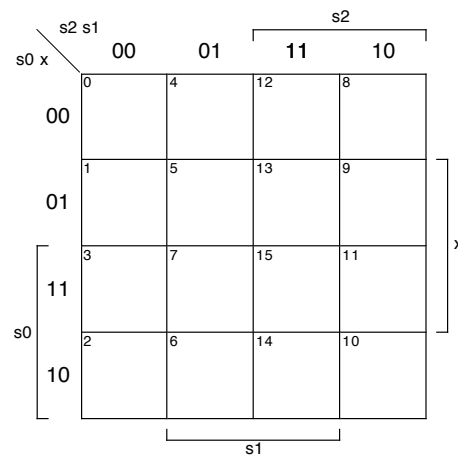
k2 =  
# of gates =



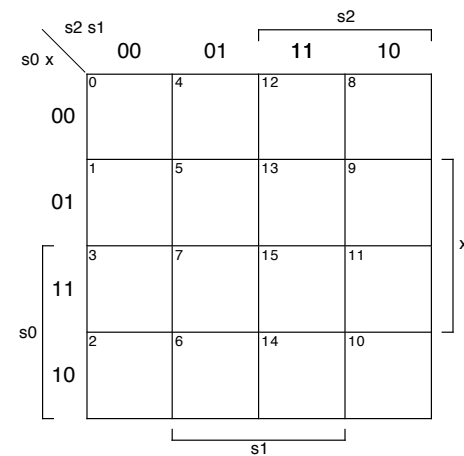
j1 =  
# of gates =



k1 =  
# of gates =



j0 =  
# of gates =



k0 =  
# of gates =

Total # of gates for J-K flip-flops (don't count z) =